

EAST SEARCH

4/4/2007

| L# | Hits | Search String | Databases |
|-----|-------|---|--|
| S1 | 58261 | (augmented near2 reality) or (computer near2 vision) or (video near2 processing) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S2 | 2664 | S1 and (camera with captur\$3 with image) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S3 | 12 | S2 and (track\$3 with movement with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S4 | 274 | S2 and (captur\$3 with image with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S5 | 5 | S2 and (captur\$3 with visual with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S6 | 1 | S2 and (identify\$3 with natural with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S7 | 15 | S2 and (identify\$3 with surface with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S8 | 496 | S2 and (image near2 sequence) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S9 | 327 | S2 and (feature with (position or location)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S10 | 32 | S2 and ((3-dimensional or three-dimensional) with surface with (location or orientation)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S11 | 2 | S2 and (coplanar with feature with image) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S12 | 265 | S2 and ((flat or (two-dimensional or 2-dimensional)) with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S13 | 1 | S2 and ((irregular near2 body) with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S14 | 8 | S2 and (supplemental near2 image) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S15 | 6 | S2 and (superimpos\$3 with (3-dimensional or three-dimensional) near2 (view or object)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S16 | 2 | S2 and (compar\$3 with feature with contrast) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S17 | 0 | S2 and (compar\$3 with feature with uniqueness) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S18 | 8 | S2 and (compar\$3 with accuracy with (position or orientation or surface)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S19 | 13 | S2 and (select\$3 with feature with (size or range)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S20 | 36 | S2 and (measur\$3 with distance with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S21 | 26 | S2 and ((location or orientation) with surface with (size or range)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S22 | 10 | S2 and (predict\$3 with position with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S23 | 0 | S2 and (search\$3 with feature with zone) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S24 | 18 | S2 and (search\$3 with feature with (range or window)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S25 | 3 | S2 and (surface with (fiducial or reference) with marker) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S26 | 45 | S2 and ((fiducial or reference) with marker) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S27 | 5 | S2 and ((fiducial or reference) with marker with (pattern or "square shaped")) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S28 | 49 | S2 and ((surface or camera) with (movement or mov\$3) with environment) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S29 | 6 | S2 and (surface with visual with appearance) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S30 | 231 | S3 or S5 or S6 or S7 or S10 or S11 or S13 or S14 or S15 or S16 or S18 or S19 or S20 or S2 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S31 | 1066 | S4 or S8 or S9 or S12 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S32 | 157 | S30 and S31 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S33 | 231 | S30 or S32 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S34 | 19 | S33 and (S5 or S6 or S7) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S35 | 18 | S33 and S24 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S36 | 58276 | (augmented near2 reality) or (computer near2 vision) or (video near2 processing) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S37 | 2664 | S36 and (camera with captur\$3 with image) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S38 | 12 | S37 and (track\$3 with movement with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S39 | 274 | S37 and (captur\$3 with image with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S40 | 5 | S37 and (identify\$3 with visual with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S41 | 1 | S37 and (identify\$3 with natural with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |

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| S42 | 15 | S37 and (identify\$3 with surface with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S43 | 496 | S37 and (image near2 sequence) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S44 | 327 | S37 and (feature with (position or location)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S45 | 32 | S37 and ((3-dimensional or three-dimensional) with surface with (location or orientation)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S46 | 2 | S37 and (coplanar with feature with image) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S47 | 265 | S37 and ((flat or (two-dimensional or 2-dimensional)) with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S48 | 1 | S37 and ((irregular near2 body) with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S49 | 8 | S37 and (supplemental near2 image) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S50 | 6 | S37 and (superimpos\$3 with (3-dimensional or three-dimensional) near2 (view or object)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S51 | 2 | S37 and (compar\$3 with feature with contrast) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S52 | 8 | S37 and (compar\$3 with accuracy with (position or orientation or surface)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S53 | 13 | S37 and (select\$3 with feature with (size or range)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S54 | 36 | S37 and (measur\$3 with distance with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S55 | 26 | S37 and ((location or orientation) with surface with (size or range)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S56 | 10 | S37 and (predict\$3 with position with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S57 | 18 | S37 and (search\$3 with feature with (range or window)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S58 | 3 | S37 and (surface with (fiducial or reference) with marker) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S59 | 45 | S37 and ((fiducial or reference) with marker) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S60 | 5 | S37 and ((fiducial or reference) with marker with (pattern or "square shaped")) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S61 | 49 | S37 and ((surface or camera) with (movement or mov\$3) with environment) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S62 | 6 | S37 and (surface with visual with appearance) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S63 | 231 | S38 or S40 or S41 or S42 or S45 or S46 or S48 or S49 or S50 or S51 or S52 or S53 or S54 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S64 | 1066 | S39 or S43 or S44 or S47 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S65 | 157 | S63 and S64 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| S66 | 231 | S63 or S65 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L1 | 64145 | (augmented near2 reality) or (computer near2 vision) or (video near2 processing) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L2 | 3164 | L1 and (camera with captur\$3 with image) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L3 | 14 | L2 and (track\$3 with movement with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L4 | 319 | L2 and (captur\$3 with image with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L5 | 8 | L2 and (identify\$3 with visual with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L6 | 1 | L2 and (identify\$3 with natural with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L7 | 21 | L2 and (identify\$3 with surface with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L8 | 596 | L2 and (image near2 sequence) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L9 | 413 | L2 and (feature with (position or location)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L10 | 38 | L2 and ((3-dimensional or three-dimensional) with surface with (location or orientation)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L11 | 2 | L2 and (coplanar with feature with image) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L12 | 303 | L2 and ((flat or (two-dimensional or 2-dimensional)) with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L13 | 1 | L2 and ((irregular near2 body) with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L14 | 9 | L2 and (supplemental near2 image) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L15 | 7 | L2 and (superimpos\$3 with (3-dimensional or three-dimensional) near2 (view or object)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L16 | 3 | L2 and (compar\$3 with feature with contrast) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L17 | 9 | L2 and (compar\$3 with accuracy with (position or orientation or surface)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L18 | 21 | L2 and (select\$3 with feature with (size or range)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L19 | 42 | L2 and (measur\$3 with distance with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L20 | 34 | L2 and ((location or orientation) with surface with (size or range)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L21 | 10 | L2 and (predict\$3 with position with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L22 | 20 | L2 and (search\$3 with feature with (range or window)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |

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| L23 | 4 | L2 and (surface with (fiducial or reference) with marker) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L24 | 55 | L2 and ((fiducial or reference) with marker) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L25 | 6 | L2 and ((fiducial or reference) with marker with (pattern or "square shaped")) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L26 | 62 | L2 and ((surface or camera) with (movement or mov\$3) with environment) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L27 | 6 | L2 and (surface with visual with appearance) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L28 | 281 | L3 or L5 or L6 or L7 or L10 or L11 or L13 or L14 or L15 or L16 or L17 or L18 or L19 or L20 or L21 or L22 or L23 or L24 or L25 or L26 or L27 or L28 or L29 or L30 or L31 or L32 or L33 or L34 or L35 or L36 or L37 or L38 or L39 or L40 or L41 or L42 or L43 or L44 or L45 or L46 or L47 or L48 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L29 | 1268 | L4 or L8 or L9 or L12 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L30 | 192 | L28 and L29 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L31 | 281 | L28 or L30 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L32 | 16325 | (augmented near2 reality) or (computer near2 vision) or (video near2 processing) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L33 | 1573 | 32 and (camera with captu\$3 with image) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L34 | 6 | 33 and (track\$3 with movement with surface) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L35 | 6 | 33 and (identify\$3 with visual with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L36 | 14 | 33 and (identify\$3 with surface with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L37 | 21 | 33 and ((3-dimensional or three-dimensional) with surface with (location or orientation)) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L38 | 41 | 34 or 35 or 36 or 37 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L39 | 0 | 38 and (compar\$3 with feature with contrast) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L40 | 0 | 38 and (compar\$4 with feature with contrast) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L41 | 0 | 38 and (compar\$4 with feature with uniqueness) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L42 | 2 | 38 and (subset with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L43 | 3 | 38 and (size with feature) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L44 | 0 | 38 and (search near2 zone) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L45 | 3 | 38 and (contrast.CLM.) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L46 | 1 | 38 and (uniqueness.CLM.) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L47 | 1 | 38 and ("search zones".CLM.) | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |
| L48 | 3 | 45 or 46 or 47 | US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB |

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Results of search set S91:

| Document Kind | Code | Title | Issue Date | Current OR | Abstract |
|---------------|-------------|--|------------|------------|----------|
| US | 20060153469 | A1 Image processing based on ambient air attributes | 20060713 | 382/254 | |
| US | 20060152434 | A1 Calibrating real and virtual views | 20060713 | 345/8 | |
| US | 20060139314 | A1 Interactive video display system | 20060629 | 345/156 | |
| US | 20060133642 | A1 Image recognition facilitation using remotely sourced content | 20060622 | 382/100 | |
| US | 20060132467 | A1 Method and apparatus for calibrating a camera-based whiteboard scanner | 20060622 | 345/178 | |
| US | 20060115157 | A1 Image processing device, image device, image processing method | 20060601 | 382/190 | |
| US | 20060091215 | A1 Two-dimensional code and information processing method | 20060504 | 235/462.1 | |
| US | 20060088187 | A1 Method and apparatus for situation recognition using optical information | 20060427 | 382/103 | |
| US | 20060079324 | A1 Image display system, image processing system, and video game system | 20060413 | 463/30 | |
| US | 20060073892 | A1 Image display system, information processing system, image processing system, and video g | 20060406 | 463/34 | |
| US | 20060071946 | A1 Information processing method and apparatus | 20060406 | 345/633 | |
| US | 20060050386 | A1 Catadioptric single camera systems having radial epipolar geometry and methods and means | 20060309 | 359/471 | |

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|-------------------|---|---------------------|
| US 20060036947 A1 | User interface controller method and apparatus for a handheld electronic device | 20060216 715/722 |
| US 20060022962 A1 | Size/scale and orientation determination of a pointer in a camera-based touch system | 20060202 345/175 |
| US 20060013441 A1 | Image monitoring method, image monitoring apparatus and storage media | 20060119 382/103 |
| US 20060013440 A1 | Gesture-controlled interfaces for self-service machines and other applications | 20060119 382/103 |
| US 20060008268 A1 | Three-dimensional image processing apparatus, optical axis adjusting method, and optical axis | 20060112 396/310 |
| US 20060004280 A1 | Placement information estimating method and information processing device | 20060105 600/414 |
| US 20050289590 A1 | Marketing platform | 20051229 725/37 |
| US 20050288078 A1 | Game | 20051229 463/1 |
| US 20050285878 A1 | Mobile platform | 20051229 345/633 |
| US 20050284937 A1 | Automated dimensional inspection | 20051229 235/437 |
| US 20050278098 A1 | Vehicular impact reactive system and method | 20051215 701/45 |
| US 20050276444 A1 | Interactive system and method | 20051215 382/103 |
| US 20050272501 A1 | Automated game monitoring | 20051208 463/29 |
| US 20050264555 A1 | Interactive system and method | 20051201 345/419 |
| US 20050264433 A1 | Image display apparatus, image display method, measurement apparatus, measurement method | 20051201 340/937 |
| US 20050257748 A1 | Apparatus and methods for the volumetric and dimensional measurement of livestock | 20051124 119/51.02 |
| US 20050256391 A1 | Information processing method and apparatus for finding position and orientation of targeted li | 20051117 600/407 |
| US 20050254726 A1 | Methods, systems, and computer program products for imperceptibly embedding structured li | 20051117 382/285 |
| US 20050253870 A1 | Marker placement information estimating method and information processing device | 20051117 345/633 |
| US 20050248729 A1 | Selectable projector and imaging modes of display table | 20051110 353/71 |
| US 20050248539 A1 | Apparatus and method for detecting a pointer relative to a touch surface | 20051110 345/173 |
| US 20050234333 A1 | Marker detection method and apparatus, and position and orientation estimation method | 20051020 600/426 |
| US 20050231713 A1 | Imaging semiconductor structures using solid state illumination | 20051020 356/237.1 |
| US 20050227217 A1 | Template matching on interactive surface | 20051013 434/337 |
| US 20050215879 A1 | Accuracy evaluation of video-based augmented reality enhanced surgical navigation systems | 20050929 600/407 |
| US 20050213807 A1 | System and method for excluding extraneous features from inspection operations performed | 20050929 382/152 |
| US 20050213790 A1 | Methods for using wireless phones having optical capabilities | 20050929 382/100 |
| US 20050195383 A1 | Method for obtaining information about objects in a vehicular blind spot | 20050908 356/4.01 |
| US 20050190972 A1 | System and method for position determination | 20050901 382/218 |
| US 20050189411 A1 | Systems and methods for merchandise checkout | 20050901 235/383 |
| US 20050185054 A1 | System, method and article of manufacture for tracking a head of a camera-generated image | 20050825 348/169 |
| US 20050180623 A1 | Method and apparatus for scanning three-dimensional objects | 20050818 382/154 |
| US 20050163343 A1 | Movable body circumstance monitoring apparatus | 20050728 382/103 |
| US 20050162409 A1 | Projector and camera arrangement with shared optics and optical marker for use with whitebo | 20050728 345/173 |
| US 20050159916 A1 | Information processing apparatus, and information processing method | 20050721 702/151 |
| US 20050149877 A1 | Graphical user interface for 3-D in-vivo imaging | 20050707 715/764 |
| US 20050149231 A1 | Method and a system for programming an industrial robot | 20050707 700/264 |
| US 20050145786 A1 | Phantom calibration device for low level light imaging systems | 20050707 250/252.1 |
| US 20050128196 A1 | System and method for three dimensional modeling | 20050616 345/420 |
| US 20050083248 A1 | Mobile face capture and image processing system and method | 20050421 345/8 |
| US 20050069196 A1 | Index identification method and apparatus | 20050331 382/154 |
| US 20050069174 A1 | Position and orientation estimating method and apparatus | 20050331 382/103 |
| US 20050054910 A1 | Optical image-based position tracking for magnetic resonance imaging applications | 20050310 600/411 |
| US 20050036672 A1 | Three-dimensional active vision with glyph address carpet | 20050217 382/154 |
| US 20050033142 A1 | Method of indexing biological imaging data using a three-dimensional body representation | 20050210 600/407 |
| US 20050018058 A1 | Method and system for reconstructing 3D interactive walkthroughs of real-world environments | 20050127 348/239 |
| US 20050012830 A1 | Autonomous camera having exchangeable behaviours | 20050120 348/231.99 |
| US 20050008343 A1 | Producing video and audio-photos from a static digital image | 20050113 386/121 |

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|-------------------|---|---------------------|
| US 20040258314 A1 | Region segmentation and characterization systems and methods for augmented reality | 20041223 382/224 |
| US 20040258306 A1 | Fiducial designs and pose estimation for augmented reality | 20041223 382/181 |
| US 20040258152 A1 | System and method for using motion vectors for object tracking | 20041223 375/240.16 |
| US 20040247193 A1 | Method and apparatus for article inspection | 20041209 382/243 |
| US 20040240750 A1 | Method and system for producing formatted data related to geometric distortions | 20041202 382/275 |
| US 20040239756 A1 | Method and apparatus for computing error-bounded position and orientation of panoramic camera | 20041202 348/36 |
| US 20040223058 A1 | Systems and methods for multi-resolution image processing | 20041111 348/207.1 |
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| L38 | 41 | 34 or 35 or 36 or 37 | US-PGPUB |
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| L48 | 3 | 45 or 46 or 47 | US-PGPUB |

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